Automatic radar plotting aid

A marine radar with automatic radar plotting aid (ARPA) capability can create tracks using radar contacts. The system can calculate the tracked object's course, speed and closest point of approach (CPA), thereby knowing if there is a danger of collision with the other ship or landmass.

Development of ARPA started after the accident when the Italian liner SS Andrea Doria collided in dense fog and sank off the east coast of the United States. ARPA radars started to emerge in the 1960s and, with the development of microelectronics. The first commercially available ARPA was delivered to the cargo liner MV Taimyr in 1969 and was manufactured by Norcontrol, now a part of Kongsberg Maritime. ARPA-enabled radars are now available even for small yachts.

History

The availability of low cost microprocessors and the development of advanced computer technology during the 1970s and 1980s have made it possible to apply computer techniques to improve commercial marine RADAR systems. Radar manufactures used this technology to create the Automatic Radar Plotting Aids. ARPAs are computer assisted radar data processing systems which generate predictive vectors and other ship movement information.

The International Maritime Organization (IMO) has set out certain standards amending the International Convention for the Safety of Life at Sea requirements regarding the carrying of suitable automated radar plotting aids. The primary function of ARPAs can be summarized in the statement found under the IMO Performance Standards. It states a requirement of ARPAs: "to improve the standard of collision avoidance at sea: Reduce the workload of observers by enabling them to automatically obtain information so that they can perform as well with multiple targets as they can by manually plotting a single target". As we can see from this statement the principal advantages of ARPA are a reduction in the workload of bridge personnel and fuller and quicker information on selected targets.

A typical ARPA gives a presentation of the current situation and uses computer technology to predict future situations. An ARPA assesses the risk of collision, and enables operator to see proposed maneuvers by own ship.

While many different models of ARPAs are available on the market, the following functions are usually provided:

1. True or relative motion radar presentation.
2. Automatic acquisition of targets plus manual acquisition.
3. Digital read-out of acquired targets which provides course, speed, range, bearing, closest point of approach (CPA, and time to CPA (TCPA).
4. The ability to display collision assessment information directly on the Plan Position Indicator (PPI), using vectors (true or relative) or a graphical Predicted Area of Danger (PAD) display.
5. The ability to perform trial maneuvers, including course changes, speed changes, and combined course/speed changes.
6. Automatic ground stabilization for navigation purposes. ARPA processes radar information much more rapidly than conventional radar but is still subject to the same limitations. ARPA data is only as accurate as the data that comes from inputs such as the gyro and speed log.

**Standalone and integral ARPAs**

Over the past 10 years, the most significant changes to the ARPA systems have been in their design. The majority of ARPAs manufactured today integrate the ARPA features with the radar display.

The initial development and design of ARPAs were stand-alone units. That is because they were designed to be an addition to the conventional radar unit. All of the ARPA functions were installed on board as a separate unit but needed to be interfaced with existing equipment to get the basic radar data. The primary benefits were cost and time savings. This of course was not the most ideal situation and eventually it was the integral ARPA that replaced the stand-alone unit.

The modern integral ARPA combines the conventional radar data with the computer data processing systems into one unit. The main operational advantage is that both the radar and ARPA data are readily comparable.

**ARPA displays**

From the time radar was first introduced to the present day the radar picture has been presented on the screen of a cathode ray tube. Although the cathode ray tube has retained its function over the years, the way in which the picture is presented has changed considerably. From about the mid-1980s the first raster-scan displays appeared. The radial-scan PPI was replaced by a raster-scan PPI generated on a television type of display. The integral ARPA and conventional radar units with a raster-scan display will gradually replace the radial-scan radar sets.

The development of commercial marine radar entered a new phase in the 1980s when raster-scan displays that were compliant with the IMO Performance Standards were introduced.

The radar picture of a raster-scan synthetic display is produced on a television screen and is made up of a large number of horizontal lines which form a pattern known as a raster. This type of display is much more complex than the radial-scan synthetic display and requires a large amount of memory. There are a number of advantages for the operator of a raster-scan display and concurrently there are some deficiencies too. The most obvious advantage of a raster-scan display is the brightness of the picture. This allows the observer to view the screen in almost all conditions of ambient light. Out of all the benefits offered by a raster-scan radar it is this ability which has assured its success. Another difference between the radial-scan and raster-scan displays is that the latter has a rectangular screen. The screen size is specified by the length of the diagonal and the width and height of the screen with an approximate ratio of 4:3. The raster-scan television tubes have a much longer life than a traditional radar cathode ray tube (CRT). Although the tubes are cheaper over their counterpart, the complexity of the signal processing makes it more expensive overall.
Raster-scan PPI

The IMO Performance Standards for radar to provide a plan display with an effective display diameter of 180mm, 250mm, or 340mm depending upon the gross tonage of the vessel. With the diameter parameters already chosen, the manufacturer has then to decide how to arrange the placement of the digital numerical data and control status indicators. The raster-scan display makes it easier for design engineers in the way auxiliary data can be written.

References

- Electronic maps for ARPA Radar in all Russia ports [3]

Article Sources and Contributors

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